

English Version

Public transport - Road vehicle scheduling and control systems - Part 7: System and network architecture

Transport public - Systèmes de planification et de contrôle des véhicules routiers - Partie 7 : Architecture
Système et Réseau

Öffentlicher Verkehr - Planungs- und Steuerungssysteme für Straßenfahrzeuge - Teil 7:
System- und Netzwerkarchitektur

This Technical Specification (CEN/TS) was approved by CEN on 8 December 2019 for provisional application.

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EUROPEAN COMMITTEE FOR STANDARDIZATION
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Contents

Page

European foreword	4
Introduction	5
1 Scope.....	7
2 Normative references.....	7
3 Terms and definitions	7
4 Symbols and abbreviations	9
5 Design principles	9
5.1 Introduction.....	9
5.2 Design goals	10
5.2.1 Enabling communications	10
5.2.2 Enabling interoperability	10
5.2.3 Ease of configuration	10
5.2.4 Quality of monitoring	10
5.2.5 Maintainability	10
5.2.6 Migration.....	10
5.2.7 Supporting fleet changes.....	10
6 Network architecture	11
6.1 Introduction.....	11
6.2 Network overview	11
6.3 Gateways to other networks	11
6.4 IP addressing.....	12
6.4.1 General addressing considerations.....	12
6.4.2 Address space.....	12
6.4.3 Manual assignment	13
6.4.4 Automatic assignment.....	13
6.5 Name registration and resolution of modules	14
6.5.1 Domain name options	14
6.5.2 Unicast Domain Name System (DNS)	15
6.5.3 Multicast Domain Name System (mDNS).....	15
6.6 Communication Protocols	16
6.6.1 HyperText Transfer Protocol (HTTP)	16
6.6.2 File Transfer Protocol (FTP)	16
6.6.3 Secure Shell (SSH).....	16
6.6.4 Multicast User Datagram Protocol (Multicast-UDP)	16
6.6.5 Session control.....	17
6.6.6 Data Multicast	17
6.6.7 Real-time Transport Protocol (RTP)	18
6.6.8 Network Time Protocol (NTP) / Simple Network Time Protocol (SNTP).....	18
6.6.9 Message Queuing Telemetry Transport (MQTT)	18
6.7 Network security.....	18
6.8 Considerations on coupled vehicles.....	18
7 Service architecture.....	19
7.1 Service oriented architecture (SOA).....	19
7.2 Service Information	19

7.2.1	Service framework options	19
7.2.2	Manual configuration	19
7.2.3	Configuration using DNS-SD	20
7.3	Communication Types	21
7.3.1	Event Triggered Data	21
7.3.2	Streaming of Data	21
7.3.3	High Frequency Data	21
7.4	Data Structure	21
7.4.1	Data structure options	21
7.4.2	XML	22
7.4.3	JSON	22
	Annex A (informative) Example usages	23
A.1	Typical vehicle network architecture	23
A.2	Function and service groups	24
	Bibliography	25

European foreword

This document (CEN/TS 13149-7:2020) has been prepared by Technical Committee CEN/TC 278 “Intelligent transport systems”, the secretariat of which is held by NEN.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN shall not be held responsible for identifying any or all such patent rights.

This document supersedes CEN/TS 13149-7:2015.

In comparison with the previous edition, the following technical modifications have been made:

- reference to normative service specifications dependent on this document;
- addition of reference to MQTT;
- restructuring of SRV record.

This document is Part 7 of a series of European Standards and Technical Specifications that includes:

- CEN/TS 13149-7, *Public transport – Road vehicle scheduling and control systems – Part 7: System and network architecture* [this document];
- CEN/TS 13149-8, *Public transport – Road vehicle scheduling and control systems – Part 8: Physical layer for IP communication*;
- CEN/TS 13149-9, *Public transport – Road vehicle scheduling and control systems – Part 9: Time service* [currently at voting stage];
- CEN/TS 13149-10, *Public transport – Road vehicle scheduling and control systems – Part 10: Location service* [currently at voting stage];
- CEN/TS 13149-11, *Public transport – Road vehicle scheduling and control systems – Part 11: Vehicle platform interface service* [currently at voting stage].

According to the CEN/CENELEC Internal Regulations, the national standards organisations of the following countries are bound to announce this Technical Specification: Austria, Belgium, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Norway, Poland, Portugal, Republic of North Macedonia, Romania, Serbia, Slovakia, Slovenia, Spain, Sweden, Switzerland, Turkey and the United Kingdom.

Introduction

This Technical Specification is Part 7 of a series of European Standards and Technical Specifications. The scope of this series is on-board data communication systems on public transport vehicles.

Public Transport (PT) vehicles have an increasing array of information and communications systems, including ticket machines, Automated Vehicle Location (AVL) systems, destination displays, passenger announcement systems, vehicle monitoring systems, etc. Other systems are beginning to be included such as advertising screens, tourist guides, WiFi “hotspots” and infotainment.

In addition, equipped PT vehicle will usually have a communications facility to enable voice and data to be exchanged with the control centre, other PT vehicles, PT infrastructure and roadside devices for instance in requesting priority at traffic signals. Many types of communication channel are used including public and private wireless communication networks.

These systems may be provided by a number of different suppliers and may need to be integrated. For instance:

- a ticket machine may need location information to update fare stages;
- next-stop and destination information may be drawn from schedule information held in the ticket machine;
- vehicle location systems may be used to drive signal priority requests.

As data exchange between functional units becomes more widespread, a networked approach begins to become efficient. With standardized underlying technology, the PT vehicle begins to look like a local area network: making use of IEEE 802 communications and the Internet Protocol (IP) suite.

Without a clear technology framework, integrating these systems would require complex technical discussions every time a device is procured. The existing EN 13149 standards recognized this long ago in respect of the core vehicle systems, but these have not been adapted to IP networking.

Six historical parts of EN 13149, namely Parts 1 to 6, have now been withdrawn in favour of the new IP-based approach. The core of this new approach was specified in two Technical Specifications (TS):

- CEN/TS 13149-7 specifies the Network and System Architecture for on board equipment. It describes basic principles of communications including a general description of the network topology, addresses schematics, basic network services, a system overview and basic module architecture.
- CEN/TS 13149-8 specifies the Physical Layer for IP-communication networks on board PT vehicles. This part specifies the cables, connectors and other equipment including pin assignment and environmental requirements.

Building on this, a series of specific services are being specified:

- CEN/TS 13149-9, specifying the structure to be used by a service providing time data to the on-bus network;
- CEN/TS 13149-10, specifying the structure to be used by a service providing location data to the on-bus network, specifically relating to Global Navigational Satellite Systems (GNSS);
- CEN/TS 13149-11, specifying the structure to be used by a service providing data from the vehicle platform to the on-bus network, using the Fleet Management System (FMS) for source data.

These documents draw on large scale trials undertaken within European projects such as EBSF (the “European Bus System of the Future” project) and its successors, together with technical developments which have since been adopted by programmes such as the German IBIS-IP platform [1] and, more recently, the European platform ITxPT [2]. This has ensured not only that the CEN specifications are robustly proved in practice, but also that they have the support of many key system developers and operators.

With these Technical Specifications, it will be easier to achieve:

- more efficient development of PT components;
- lower cost, lower risks and a smoother on board integration of PT equipment;
- more efficient operation and maintenance of on board PT equipment;
- high quality intermodal passenger services based on intermodal PT information;
- integration of new PT services.

As an IP based solution, this Technical Specification draws on a range of IETF Requests for Comment (RFCs), not all of which may be formal standards. A list of those cited is presented in the Bibliography.